## Control module display stand



The PowerXL DG1 powered control module display stand is designed to be a compact, interactive sales and training tool. It simulates a fully line-powered PowerXL DG1 variable frequency drive with finger-safe 24 Vdc power with a small fan powered by an analog output to simulate a full-size three-phase industrial motor. Five demonstration exercises have been provided in this document to walk through the product functionality.

## **Display stand features**

- 24 Vdc powered control module and motor
- Full DG1 software functionality
- Communication and PC Tool capabilities
- External fault and jog inputs
- Ready light and speed potentiometer

Verify Initial Configuration	<ol> <li>P: Parameters → P1: Basic Parameters → P1.13: Local Reference → Set to "Al2"</li> <li>P: Parameters → P3: Digital Input → P3.8: Fault Reset → Set to "DigIN:ForceOpen"</li> <li>P: Parameters → P4: Analog Outputs → P4.1: AO1 Mode → Set to "0-10 V"</li> <li>P: Parameters → P5: Digital Outputs → P5.2: RO1 Function → Change to "Ready"</li> <li>Upload the parameters to the keypad by following the pathway below (60 second upload). [P: Parameters → P21: System → P21.1: Basic Settings → P21.1.4: Up to Keypad → Change to "YES"]</li> <li>Press LOC/REM button if in remote mode, then press the OK key (Remote light will be off).</li> </ol>
Pilot Device Control	<ol> <li>Press green START key and adjust potentiometer between 30 and 60 Hz to change the motor's speed.</li> <li>The white LED light is set to display a "Ready" signal. Change the reference to "External Fault."         [P: Parameters → P5: Digital Outputs → P5.2: RO1 Function → Change to "External Fault/Warning"]     </li> <li>Press the red EXT FLT, which will stop the motor and display a fault message.         The LED light will illuminate with the fault.     </li> <li>Clear the external fault by pressing-and-holding the "BACK/RESET" button on the keypad for 2 seconds.</li> </ol>
Keypad Speed Control	<ol> <li>Change the speed reference from potentiometer to the keypad:         <ul> <li>[P: Parameters → P1: Basic Parameters → P1.14: Local Reference → Change to "Keypad"]</li> </ul> </li> <li>Set the keypad reference frequency by following the below pathway:         <ul> <li>[O: Operate → R12: Keypad Reference → Change to a value between "40–60 Hz"]</li> <li>Press the green START key to start the motor and adjust the keypad reference to 30 Hz, then press STOP.</li> <li>Follow Steps 1 and 2 to reset the speed reference to "Al2" and the keypad reference back to "0.00 Hz".</li> </ul> </li> </ol>



DO NOT RESET THE DEMO TO USE DEFAULT PARAMETER VALUES. THIS WILL CAUSE THE SOFTWARE TO RESET, REMOVING THE SPECIAL SIMULATION FUNCTIONALITY OF THIS DEMO.



Favorites and Multi-Monitoring Menus	<ol> <li>Navigate the parameter menu and add the following to favorites using the left-soft key: [P1.1: Min Frequency / P21.1.14: Fan Control / P1.3: Acceleration Time / P9.3: External Fault]</li> <li>Go to the Main menu, then use the arrow keys to view the Favorites menu.</li> <li>Delete the parameters from the Favorites menu for future demos by using the left soft key.</li> <li>Navigate to the Multi-Monitoring menu and change the default references to those listed below: [M: Monitor → M46: Multi-Monitor → Change all three default values to: M9: Unit Temp. / M16: Input Status / M20: Relay Status]</li> <li>Reset the multi-monitoring values to [M1: Output Freq / M2: Freq Ref / M3: Motor Speed].</li> </ol>
Safe-Torque OFF and Keypad Parameter Download	<ol> <li>Locate the YELLOW terminals on the control module. Disconnect the terminal block from the unit.</li> <li>A Safety-Torque OFF fault should occur because the STO circuit was opened due to the terminal removal. Replace the terminal and reset the fault by using the "BACK/RESET" button.</li> <li>Download the parameter set that was uploaded in section one by following the pathway below:</li> </ol>

[P: Parameters  $\rightarrow$  P21: System  $\rightarrow$  P21.1: Basic Settings  $\rightarrow$  P21.15: Down from Keypad  $\rightarrow$  Change to "YES"]

## **Control terminal layout**

+10V	1	DO1	14			
AI1+	2	24Vo	15			
AI1-	3	GND	16			
Al2+	4	AO1+	17			
Al2-	5	AO2+	18			
GND	6	24Vi	19			
DIN5	7	DIN1	20			
DIN6	8	DIN2	21			
DIN7	9	DIN3	22			
DIN8	10	DIN4	23			
СМВ	11	CMA	24			
GND	12	А	25			
24Vo	13	В	26			
R3NO	27	R3CM	31			
R1NC	28	R2NC	32			
R1CM	29	R2CM	33			
R1NO	30	R2NO	34			



## Additional documentation and product training is available at **www.eaton.com/DG1**

For technical support, contact EatonCare at 1-877-ETN-CARE (386-2273) x2 x6 x3

Follow us on social media to get the latest product and support information.



Eaton 1000 Eaton Boulevard Cleveland, OH 44122 United States

Eaton.com

© 2016 Eaton All Rights Reserved Printed in USA Publication No. MZ040005EN / Z18628 September 2016

Eaton is a registered trademark.

All other trademarks are property of their respective owners.

